

# Prognostics Testbed

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#### **Problem**

#### **Motivation**

To facilitate research in prognostics, it is imperative to have a hardware testbed that mimics the complexities and issues encountered for a real system.

Such a system will support

- Algorithm development
- Testing and validation of prognostic tools
- Benchmarking of different approaches
- Development of metrics for prognostics
- Collection and dissemination of run-to-failure data

#### Goal

 Demonstrate ability to distinguish between components at different health states having similar external observables and then to predict the end of life

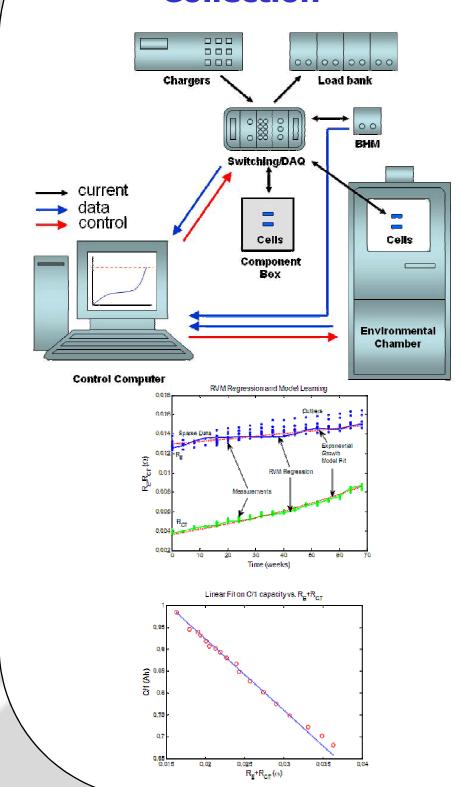
#### **Requirements**

The testbed shall:

- Resemble a system that has real-world relevance
- Allow for repeated run-to-failure of components
- Perform run-to-failure in reasonable time
- Support monitoring of ground truth
- Collect data for state assessment
- Support demonstration of prognostic solutions
- Allow control of several operational and/or environmental variables
- Allow quantification of uncertainty sources
- Support repeated run-to-failure within a finite budget
- Support automated data collection during the aging

#### **System**

## **Testbed – Data Collection**



- A set of Li-ion cells
  - $\bullet$  Aging dynamics slow enough to be observable and fast enough for reasonable run-to-failure times ( $\sim\!\!1$  month)

**Experimental setup** 

- Low cost
- May be aged either inside or outside an environmental chamber
- Programmable Charger and Electronic Load
- EIS equipment for battery health monitoring (BHM)
- Sensor suite Voltage, Current, Temperature
- Custom switching circuitry
- Data acquisition system
   Computer for control and ar
- Computer for control and analysis

# B0006 Nyquist Plots Aging -0.005 -0

#### **Experimental Plan**

- Cells are cycled through charge and discharge under different load and environmental conditions set by the electronic load and environmental chamber respectively
- Periodically EIS measurements are taken to monitor the internal condition of the battery
- DAQ system collects externally observable parameters from the sensors
- Switching circuitry enables cells to be in the charge, discharge or EIS health monitoring state as dictated by the aging regime

#### Results

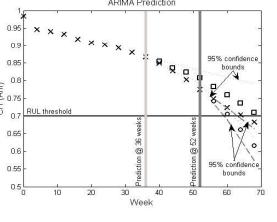
#### **Algorithm Development**

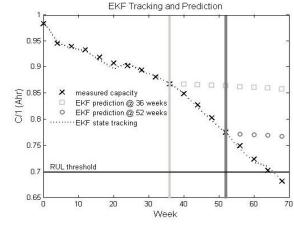
The algorithms considered so far include both model-based as well as data-driven algorithms, for example

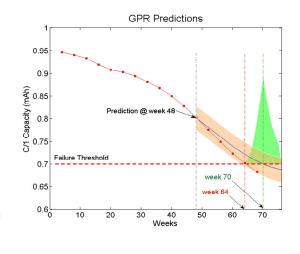
- Relevance vector machines (RVM)
- Gaussian Process Regression (GPR)
- Particle Filters (PF, RBPF)
- Neural Networks (NN)
- Random Forest Regression
- ARIMA models
- Kalman Filters

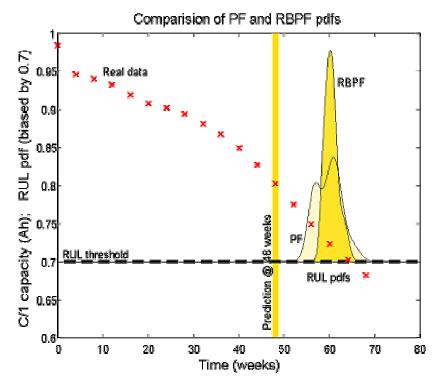
Further algorithms will be explored and results will be published to disseminate findings on advantages and disadvantages of each one.

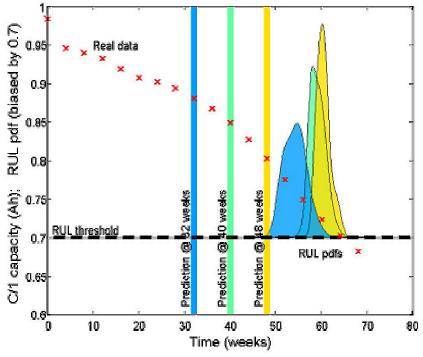
#### **Sample Results**







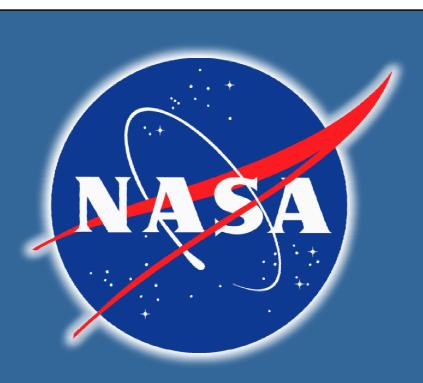




**RBPF Prediction** 

# Battery Prognostics

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#### **Problem**

#### **Electric Propulsion Space Experiment (AFRL)**

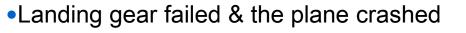


- Ammonia Arcjet onboard ARGOS (1999)
- Gases released from electrolyte decomposition resulted in a breach of the battery case, releasing superheated gas into the unit

(Courtesy: AFRL-PR-ED-TR-2001-0027)

#### **Beech A200 (Reg # N258AG)**

- Onboard generators failed to activate as starter was still engaged after ignition
- Battery completely discharged resulting in total electrical failure disabling normal landing gear extension capability





(Courtesy: NTSB, ID #SEA00LA066)

# (NASA/JPL, Artist's concept)

#### Mars Global Surveyor

The MGS failed Nov 2006

"We think that the failure was due to a software load ... The radiator for the battery pointed at the sun, the temperature went up, and battery failed...'

John McNamee Mars Exploration Program, NASA

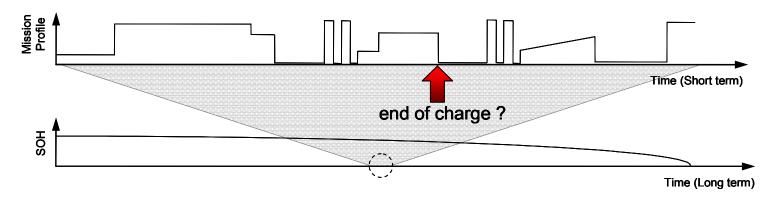
#### **Questions to be Answered**

#### Can the current mission be completed?

- Given the health of the battery, is there enough charge left for anticipated load profile (within allowable uncertainty bounds)?
- Dominant metrics: state of charge (SOC), state of health (SOH)

#### Can future missions be completed?

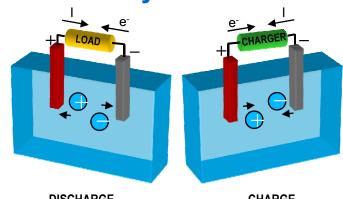
- Given the health of the battery, at what point can typical future missions not be met?
- Dominant metrics: end of life (EOL), state of health (SOH)



GOAL: Develop a model that makes a prediction of end-of-charge and end-of-life based on rapid state of health (SOH) assessment

#### Approach

#### **Battery Schematic**



**DISCHARGE** 

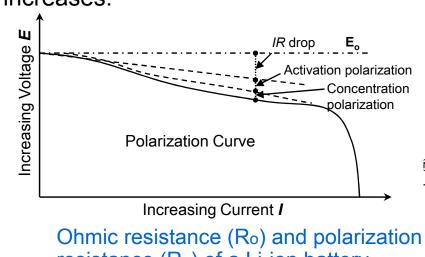
CHARGE

- The External Voltage (E) of a battery is less than its Open Circuit Potential (E<sub>0</sub>) whenever it is in use.
- •Losses are due to:

System Sensors

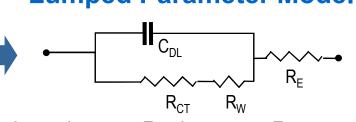
PHM/CBM Sensors

- Ro: Internal Resistance (IR drop),
- R<sub>p</sub>: Polarization Resistance
- R<sub>c</sub>: Concentration Polarization
- These losses tend to increase as the current drawn from the battery increases.



resistance (R<sub>p</sub>) of a Li-ion battery gradually increase with aging

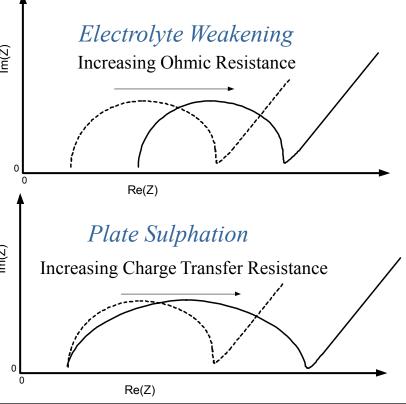
#### **Lumped Parameter Model**



Impedance = Resistance + Reactance

#### **Electrochemical Impedance** Spectroscopy (EIS)

- Carry out a frequency sweep
- Plot Capacitive (1/ωC) v/s Resistive (R) component of the Reactance
- Response is different in presence of passivation and corrosion, providing a diagnostic for the health state of battery

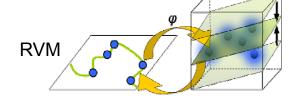


#### **Relevance Vector Machine**

- State of the art in nonlinear probabilistic regression
- Data driven learning
- Learn degradation mode

EIS

Data



#### **Particle Filter**

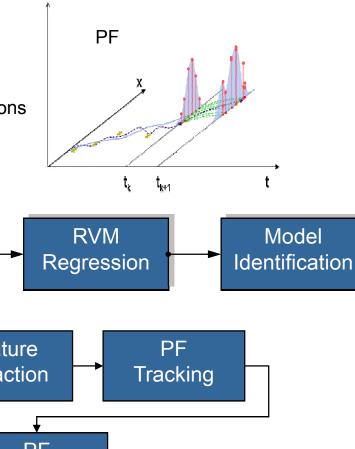
 State of the art for nonlinear non-Gaussian state estimation

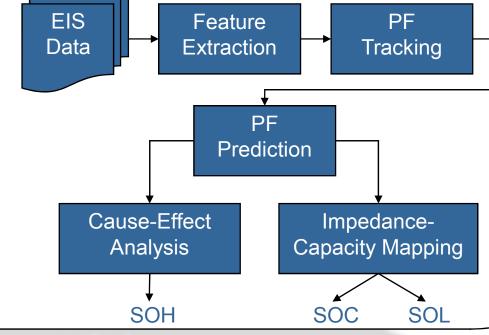
 Uses model to predict and data to correct prediction

 Sequential Monte-Carlo simulations with Importance Sampling for p-step ahead predictions

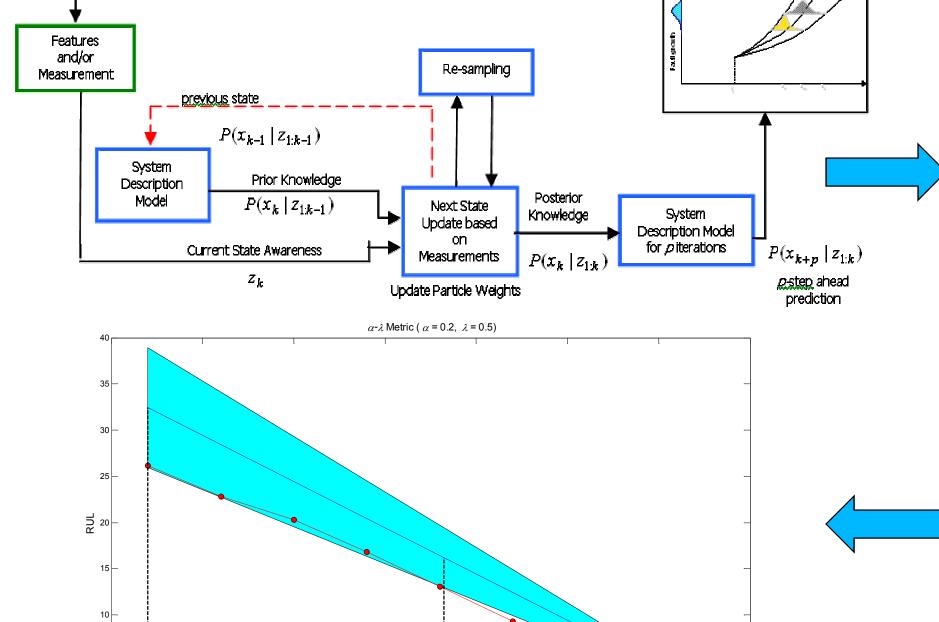
Feature

Extraction





### Results



Time Index (i)

0.025 PF Prediction 0.02 0.015  $R_{E}, R_{CT}(\Omega)$ PF Tracking 0.01 Measurements 0.005 20 30 40 50 10 60 70 Time (weeks) Particle Filter Prediction Real data

Particle Filter Output

RUL pdf (biased by 0.7) C/1 capacity (mAh); RUL threshold

Time (weeks) POC: Bhaskar Saha, **☎**(650)604-4379, ⊠ bhaskar.saha@nasa.gov

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